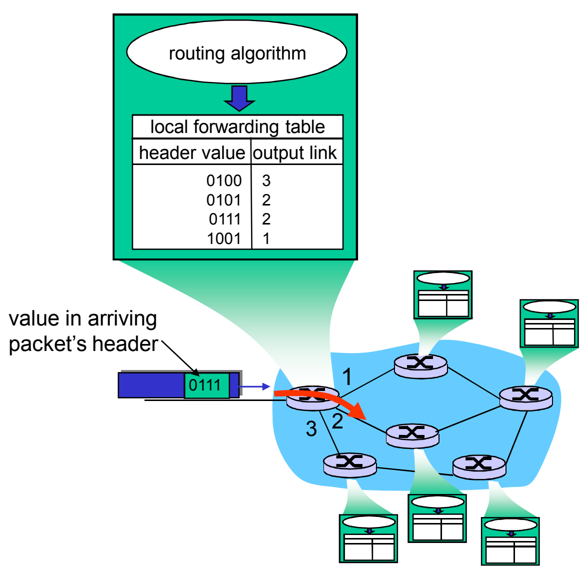
Computer Networks

Routing Algorithms

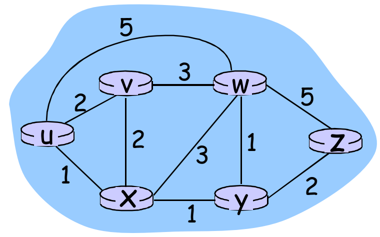
Based on Computer Networking, 4th Edition by Kurose and Ross

Interplay between routing, forwarding



Stan Kurkovsky

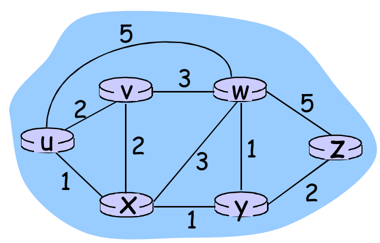
Graph abstraction



- Graph: G = (N,E)
- N = set of routers = { u, v, w, x, y, z }
- E = set of links ={ (u,v), (u,x), (v,x), (v,w), (x,w), (x,y), (w,y), (w,z), (y,z) }
- Remark: Graph abstraction is useful in other network contexts
- Example: P2P, where N is set of peers and E is set of TCP connections

Graph abstraction: costs

- c(x,x') = cost of link (x,x')
  - e.g., c(w,z) = 5
- cost could always be 1,
  or inversely related to bandwidth,
  or inversely related to congestion



- Cost of path $(x_1, x_2, x_3, \ldots, x_p) = c(x_1,x_2) + c(x_2,x_3) + \ldots + c(x_{p-1},x_p)$
- Question: What's the least-cost path between u and z ?
- Routing algorithm: algorithm that finds least-cost path

Routing Algorithm classification

Global or decentralized information?

Global:

- all routers have complete topology, link cost info
- "link state" algorithms

Decentralized:

- router knows physically-connected neighbors, link costs to neighbors
- iterative process of computation, exchange of info with neighbors
- "distance vector" algorithms

Static or dynamic?

Static:

- routes change slowly over time

Dynamic:

- routes change more quickly
  - periodic update
  - in response to link cost changes

A Link-State Routing Algorithm

Dijkstra's algorithm

- net topology, link costs known to all nodes
  - accomplished via "link state broadcast"
  - all nodes have same info
- computes least cost paths from one node ('source") to all other nodes
  - gives forwarding table for that node
- iterative: after k iterations, know least cost path to k destinations

Notation:

- c(x,y): link cost from node x to y; = ∞ if not direct neighbors
- D(v): current value of cost of path from source to dest. v
- p(v): predecessor node along path from source to v
- N': set of nodes whose least cost path definitively known

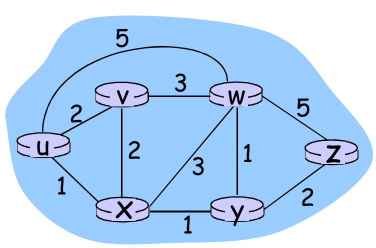
Dijsktra’s Algorithm

```
Initialization:
 N' = {u}
 for all nodes v
   if v adjacent to u
      then D(v) = c(u,v)
   else D(v) = ∞

Loop
  find w not in N' such that D(w) is a minimum
  add w to N'
  update D(v) for all v adjacent to w and not in N' :
     D(v) = min( D(v), D(w) + c(w,v) )
  /* new cost to v is either old cost to v or known
   shortest path cost to w plus cost from w to v */
until all nodes in N'
```

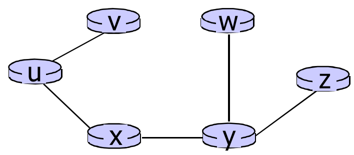

Dijkstra’s algorithm: example

Step	N'	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy	2,u	3,y			4,y
3	uxyv		3,y			4,y
4	uxyvw					4,y
5	uxyvwz					



Dijkstra's algorithm: example (2)

Resulting shortest-path tree from u:



Resulting forwarding table in u:

destination	link
v	(u,v)
x	(u,x)
y	(u,x)
w	(u,x)
z	(u,x)

Stan Kurkovsky

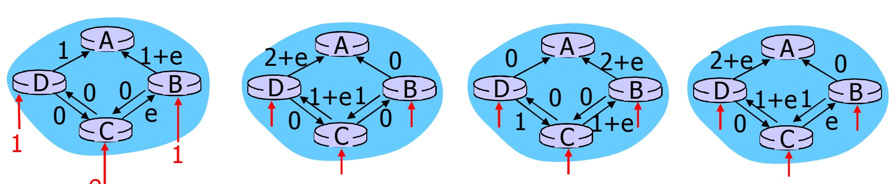
Dijkstra's algorithm, discussion

Algorithm complexity: n nodes

- each iteration: need to check all nodes, w, not in N
- n(n+1)/2 comparisons: $O(n^2)$
- more efficient implementations possible: O(nlogn)

Oscillations possible:

- e.g., link cost = amount of carried traffic



initially ... recompute routing ... recompute ... recompute

Stan Kurkovsky

Distance Vector Algorithm

Bellman-Ford Equation (dynamic programming)

- Define

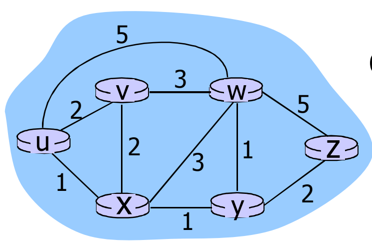
  $d_x(y)$:= cost of least-cost path from x to y

- Then

  $d_x(y) = \min \{c(x,v) + d_v(y) \}$

  where min is taken over all neighbors v of x

Bellman-Ford example



Clearly, $d_v(z) = 5$, $d_x(z) = 3$, $d_w(z) = 3$

B-F equation says:

$$
\begin{aligned}
d_u(z) &= \min \{ c(u,v) + d_v(z), \\
&\qquad c(u,x) + d_x(z), \\
&\qquad c(u,w) + d_w(z) \} \\
&= \min \{2 + 5, \\
&\qquad 1 + 3, \\
&\qquad 5 + 3\} = 4
\end{aligned}
$$

Node that achieves minimum is next hop in shortest path ➜ forwarding table

Distance Vector Algorithm

- $D_x(y)$ = estimate of least cost from x to y
- Distance vector: $\mathbf{D}_x = [D_x(y): y \in N]$
- Node x knows cost to each neighbor v: $c(x,v)$
- Node x maintains $\mathbf{D}_x = [D_x(y): y \in N]$
- Node x also maintains its neighbors' distance vectors
  - For each neighbor v, x maintains
    $\mathbf{D}_v = [D_v(y): y \in N]$

Basic idea:

- Each node periodically sends its own distance vector estimate to neighbors
- When a node x receives new DV estimate from neighbor, it updates its own DV using B-F equation:
  $Dx(y) \leftarrow minv\{c(x,v) + Dv(y)\}$ *for each node* $y \in N$
- Under minor, natural conditions, the estimate Dx(y) converge to the actual least cost dx(y)

Stan Kurkovsky

Distance Vector Algorithm

Iterative, asynchronous: each local iteration caused by:

- local link cost change
- DV update message from neighbor

Distributed:

- each node notifies neighbors *only* when its DV changes
  - neighbors then notify their neighbors if necessary

Each node:

wait for (change in local link cost of msg from neighbor)

recompute estimates

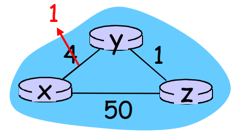
if DV to any dest has changed, *notify* neighbors

Stan Kurkovsky

Distance Vector: link cost changes

Link cost changes:

- node detects local link cost change
- updates routing info, recalculates distance vector
- if DV changes, notify neighbors



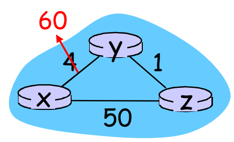
- "Good news travels fast"
  - At time t_0, *y* detects the link-cost change, updates its DV, and informs its neighbors.
  - At time t_1, *z* receives the update from *y* and updates its table. It computes a new least cost to *x* and sends its neighbors its DV.
  - At time t_2, *y* receives *z*'s update and updates its distance table. *y*'s least costs do not change and hence *y* does *not* send any message to *z*.

Stan Kurkovsky

Distance Vector: link cost changes

Link cost changes:

- good news travels fast
- bad news travels slow - "count to infinity" problem!
- 44 iterations before algorithm stabilizes

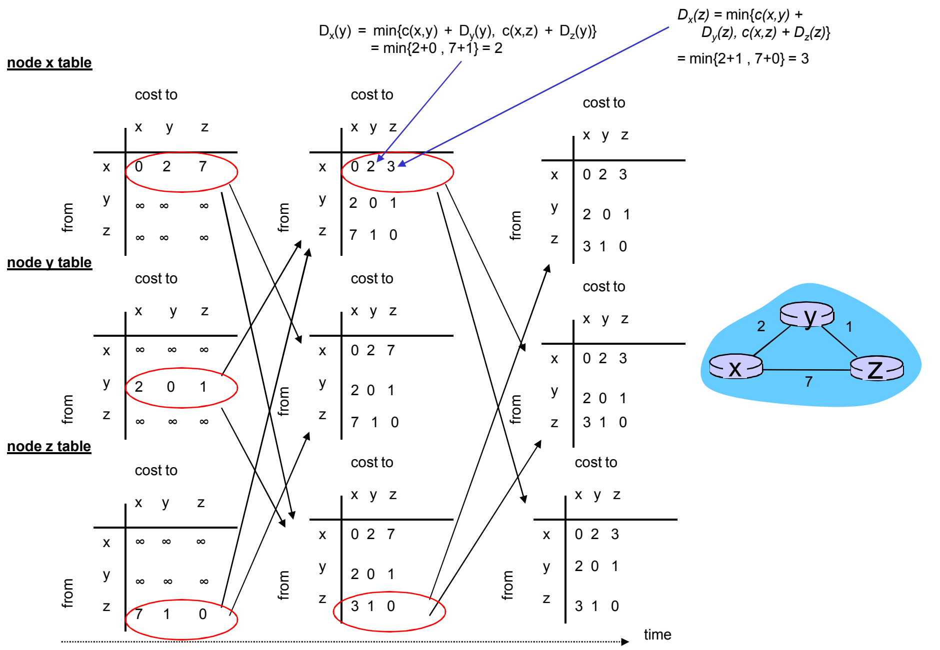


Poissoned reverse:

- If Z routes through Y to get to X :
  - Z tells Y its (Z's) distance to X is infinite (so Y won't route to X via Z)
- will this completely solve count to infinity problem?

Stan Kurkovsky

Distance Vector: example



Comparison of LS and DV algorithms

Message complexity

- LS: with n nodes, E links, O(nE) msgs sent
- DV: exchange between neighbors only
  - convergence time varies

Speed of Convergence

- LS: $O(n^2)$ algorithm requires O(nE) msgs
  - may have oscillations
- DV: convergence time varies
  - may be routing loops
  - count-to-infinity problem

Robustness: what happens if router malfunctions?

LS:

- node can advertise incorrect *link* cost
- each node computes only its *own* table

DV:

- DV node can advertise incorrect *path* cost
- each node's table used by others
  - error propagate thru network

Hierarchical Routing

Our routing study thus far - idealization

- all routers identical; network "flat" → ... *not* true in practice

scale: with 200 million destinations:
- can't store all dest's in routing tables!
- routing table exchange would swamp links!

administrative autonomy
- internet = network of networks
- each network admin may want to control routing in its own network

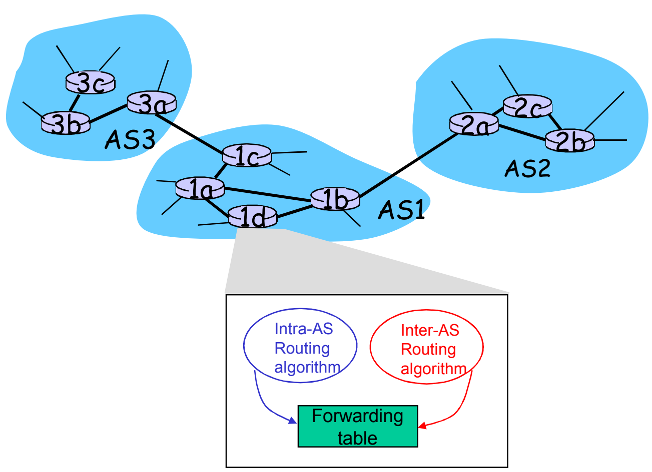
- aggregate routers into regions, "autonomous systems" (AS)
- routers in same AS run same routing protocol
  - "intra-AS" routing protocol
  - routers in different AS can run different intra-AS routing protocol

Gateway router
- Direct link to router in another AS

Stan Kurkovsky

Interconnected ASes

- Forwarding table is configured by both intra- and inter-AS routing algorithm
  - Intra-AS sets entries for internal dests
  - Inter-AS & Intra-As sets entries for external dests



Stan Kurkovsky

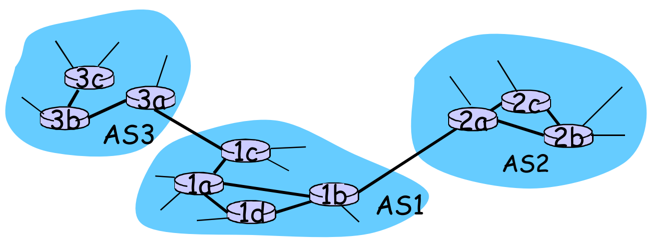
Inter-AS tasks

- Suppose router in AS1 receives datagram for which dest is outside of AS1
  - Router should forward packet towards one of the gateway routers, but which one?

AS1 needs:

1. to learn which dests are reachable through AS2 and which through AS3
2. to propagate this reachability info to all routers in AS1

Job of inter-AS routing!



Stan Kurkovsky