Multiprocessors

Instructor: Dmitri A. Gusev

Fall 2007

CS 502: Computers and Communications Technology

Lecture 13, October 17, 2007
Multiprocessors

- Idea: create powerful computers by connecting many smaller ones

  good news: works for timesharing (better than supercomputer)

  bad news: it's really hard to write good concurrent programs
            many commercial failures
Questions

• How do parallel processors share data?
  — single address space (SMP vs. NUMA)
  — message passing

• How do parallel processors coordinate?
  — synchronization (locks, semaphores)
  — built into send / receive primitives
  — operating system protocols

• How are they implemented?
  — connected by a single bus
  — connected by a network
Programming multiprocessors

• Multiprogramming is difficult:
  - Communication problems
  - Requires knowledge about the hardware
  - All parts of the program should be parallelized
Multiprocessors connected by a single bus

- Each processor is smaller than a multichip processor
- The use of caches can reduce the bus traffic
- There exists mechanisms to keep caches and memory consistent
Snooping (monitoring) protocols: locate all caches that share a block to be written. Then:

- **Write-invalidate**: The writing processor causes all copies in other caches to be invalidated before changing its local copy. Similar to write-back.
- **Write-update (broadcast)**: The write processor sends the new data (the word) over the bus. Similar to write-through.
- The role of the size of the block (broadcasting only a word, false sharing).
Write-invalidate cache coherency protocol based on a write-back policy

Each cache block is in one of the following states:
- **Read only**: the block is not written and may be shared
- **Read/Write**: the block is written (dirty) and may not be shared
- **Invalid**: the block does not have valid data
Synchronization using coherency

- Using locks (semaphores)
- Atomic swap operation

<table>
<thead>
<tr>
<th>Step</th>
<th>P1</th>
<th>P2</th>
<th>P3</th>
<th>Bus activity</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Has lock</td>
<td>Spins, testing lock=0</td>
<td>Spins, testing lock=0</td>
<td>none</td>
</tr>
<tr>
<td>2</td>
<td>Sets lock to 0 and 0 sent over bus</td>
<td>Spins, testing lock=0</td>
<td>Spins, testing lock=0</td>
<td>Write-invalidate of lock variable sent from P0</td>
</tr>
<tr>
<td>3</td>
<td>Cache miss</td>
<td>Cache miss</td>
<td>Bus decides to service P2 cache miss</td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>Waits (bus busy)</td>
<td>Lock=0</td>
<td>Cache miss for P2 satisfied</td>
<td></td>
</tr>
<tr>
<td>5</td>
<td>Lock =0</td>
<td>Swap: reads locks and sets to 1</td>
<td>Cache miss for P1 satisfied</td>
<td></td>
</tr>
<tr>
<td>6</td>
<td>Swap: reads locks and sets to 1</td>
<td>Value from swap=0 and 1 sent over bus</td>
<td>Write-invalidate of lock variable sent from P2</td>
<td></td>
</tr>
<tr>
<td>7</td>
<td>Value from swap=1 and 1 sent over bus</td>
<td>Owns the locks and updates the shared data</td>
<td>Write-invalidate of lock variable sent from P1</td>
<td></td>
</tr>
<tr>
<td>8</td>
<td>Spins, testing lock=0</td>
<td></td>
<td>None</td>
<td></td>
</tr>
</tbody>
</table>
Supercomputers

Plot of top 500 supercomputer sites over a decade:

- Single Instruction multiple data (SIMD)
- Cluster (network of workstations)
- Cluster (network of SMPs)
- Massively parallel processors (MPPs)
- Shared-memory multiprocessors (SMPs)
- Uniprocessors
Using multiple processors an old idea

- Some SIMD designs:

- Costs for the the Illiac IV escalated from $8 million in 1966 to $32 million in 1972 despite completion of only ¼ of the machine. It took three more years before it was operational!

  “For better or worse, computer architects are not easily discouraged”

Lots of interesting designs and ideas, lots of failures, few successes
Topologies

a. Crossbar

b. Omega network

a. 2-D grid or mesh of 16 nodes

b. n-cube tree of 8 nodes \((8 = 2^3 \text{ so } n = 3)\)
Clusters

• Constructed from whole computers
• Independent, scalable networks
• Strengths:
  – Many applications amenable to loosely coupled machines
  – Exploit local area networks
  – Cost effective / Easy to expand
• Weaknesses:
  – Administration costs not necessarily lower
  – Connected using I/O bus
• Highly available due to separation of memories
• In theory, we should be able to do better
Google

• Google uses thousands of processors and disks to handle thousands of queries per second
Concluding Remarks

• Evolution vs. Revolution

“More often the expense of innovation comes from being too disruptive to computer users”

“Acceptance of hardware ideas requires acceptance by software people; therefore hardware people should learn about software. And if software people want good machines, they must learn more about hardware to be able to communicate with and thereby influence hardware engineers.”